





Use of IR Technology in Sensing and Control of Ultrasonic Metal Welding

Karl Graff, Jay Eastman, Tim Frech, Yu-Ping Yang Edison Welding Institute Columbus, Ohio 43221 614.688.5000 karl_graff@ewi.org



IR - Two Fields of Use in UMW

- Sensing, control of UMW process
- Sensing vibrations created by UMW











Use of IR in Weld Sensing, Control

 Can IR image/profile be related to weld quality? ('quality' ~ weld strength)



Early IR Weld Sensing Work



Use of IR TC

IR TC

- Use IR thermocouple to focus on critical region (determined from IR camera)
- Arrow is line-of sight for IR TC





Use of IR TC

- Temperature repeatability 5 welds (400J, 60µ, 1250N average, Std. dev. 218N)
- Weld temperature correlates with weld strength
- Potential for on-line weld quality measurement





IR TC – Recent Work

- Sonobond Model 2016 Welder
- Material: 25 x 100mm x 0.9-mm
 6111 Aluminum
- Varied Power: 1500 and 2000 W
- Varied Time: 0.44, 0.66, 0.88 S
- Varied Pressure: 344, 448, and 551 MPa
- Made 3 Welds at Each Setting (54 welds)
- Recorded IR TC Signature of Each



IR Thermocouple



Typical IR TC Data





Weld Strength - Peak IR Temperature





Repeat Low, Medium, High Settings





Example: Setting Temperature Limits



No Light: Did not reach Minimum Temperature Green Light: Reached Minimum Temperature Blue Light: Exceeded Maximum Temperature



Observations

- The higher the observed temperature the higher the tensile strength
- Increasing pressure decreases observed temperature
- Increasing time and power increase observed temperature
- Higher temperatures observed in rapid sequence welding



IR Sensing of UMW Vibrations

- Early work
- Work on large plates









Initial Plate Tests



Grid of 20 Weld Locations – $\frac{1}{4}$ of Plate

Case modeled by FEA



6111 aluminum 0.9-mm thick

All Plates 200 mm x 280 mm divided into approximately 25-mm squares



FEA Modeling of UMW Plate Vibrations



Two stages in ultrasonic welding: Stage 1: Sliding of plate 1 on the Plate 2 Stage 2: weld formation Static Force was modeled by applying a pressure

Interaction between the sonotrode and the top plate was modeled by applying nodal displacements.

Interaction between the two plates was modeled by contact simulations.

Interaction between the bottom plate and the anvil was modeled by fixing the interface surface.



FEA Model of Plate Vibrations



Experimental, Modeling Results





Effects of Clamping





Rubber tip clamps







No Clamp vs. Clamp

Effect of single point clamp







Rubber Tip Clamps - AD

 Weld at AD, various clamp locations, strengths







Rubber Tip Clamps - BD

 Weld at BD, various clamp locations, strengths



THE MATERIALS JOINING EXPERTS



Observations

- Variability of IR images, strengths for "identical welds"
- Variability of strengths by weld location (AD, BD, etc)
- Modeling shows well known variations in driving impedance (this has also been modeled)
- Modeling shows HF modes but images more complex



Note on Complex Mode Shapes

FEA show HF modes



 Audible subharmonics generated during welding - show up with HF superimposed







Questions

Karl Graff Microjoining & Plastics

614.688.5000 karl_graff@ewi.org



